# Finding the scale of space

How do astronomers measure distances to the stars? Using a digital camera to record parallax shift is an accurate and authentic method that can be used in a classroom.

#### By Markus Pössel

Astronomers are remote observers, separated by great distances from the objects they study. Knowing the distance of celestial objects is crucial: it provides a key factor in distinguishing a very luminous, distant object from one that is much closer but inherently less bright – and thus in working out what the object is. Even single stars and whole galaxies can look similar – until we know that one is a billion times further away than the other, and thus in reality trillions of times brighter.

The most important astronomical method for determining distances from Earth to the stars is parallax – the apparent shift in position of a viewed object when the observer changes position. We notice the parallax effect when we look out a train window: nearby objects seem to move past much faster than distant ones. Using this effect, we can work out the distance of an object by measuring the apparent change in its position when our position as observers changes.

The challenge, of course, is accuracy. How can we make distance measurements based on parallax as accurate as possible? In this second article on measuring distances using parallax, we use an authentic method very similar to that used by astronomers, which has been adapted for use in a classroom (for the previous article, see Pössel, 2017). Instead of using angle-measuring devices (as in the previous article, based on theodolite measurements) to work out the distance



REVIEW

## Astronomy/space

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This article describes an innovative way to find the distances to celestial bodies using the parallax method. It is very suitable for students and teachers who have a keen interest in both photography and astronomy. It presents the necessary detail to be able to calculate the distance to a 'star' to a good degree of accuracy, illustrated with an example.

The activity is ideal to use with a group of students or in a workshop on astronomy or photography for advanced students.

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TEACH | Astronomy/space, Mathematics, Physics

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When we look at the sky at night, bright stars far away look similar to duller, nearer stars. Parallax measurements allow us to tell these apart.

to a 'star', here we take photographs from different positions and use these to provide the measurements we need to calculate our star's distance.

A variation of this photographic method, described later in this article, is even more authentic and accurate, although slightly more complicated. It involves using a fixed reference point outside the classroom – just as astronomers use very distant background objects (e.g. active galaxies called quasars) as fixed reference points when measuring stellar parallax, rather than relying on their telescopes pointing in the same direction for each observation.

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For these activities, you will need a digital camera, mounted (if possible) on an optical bench (see figure 1). The activities can be carried out by groups of students. Allow around 30 minutes for setting up and taking measurements, and an additional 30 minutes for the analysis and calculations.

Figure 1: Camera mounted on optical bench for easy sideways shifting

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### Materials

- Digital camera with lens of known focal length (at least 50 mm)
- Optical bench (or similar setup for moving the camera sideways and measuring the shift, such as a flat table top and a long ruler)
- Model star (a small sphere no more than 1 cm in diameter or an LED, mounted on a stick)
- Object of known length with clear markings (e.g. a metre rule), as a calibration object
- Tape measure
- Image processing programme, e.g. Adobe Photoshop, GIMP

### Procedure

1. Mount the camera on the optical bench so that you can shift the camera sideways by a known distance. The camera should be pointing at right angles to the length of the bench (figure 1). If you don't have an optical bench, tape a long ruler to the surface of a table so that you can move the camera along the ruler and measure the shift distance.

- 2. Mount the model star so that it is at eye level with the camera and a few metres away from the camera bench.
- Slide the camera to one end of bench, making sure that the star is visible through the camera. Take a photo of the star from this position.
- 4. Then, shift the camera along the optical bench so that the star is still visible through the lens. Record the distance moved, and then take another photo from this position.
- 5. Move the camera back to a central position. Now place the calibration object (e.g. a metre rule) at a right angle to the camera's direction of view and take a photo of it. This image will be used to calibrate your measurements.
- 6. Using a tape measure, find and record the distance from the camera to the metre rule.

### Calculating the star distance

The experimental situation is shown in figure 2. Here, *b* represents the shift distance along the camera baseline (the optical bench or table) between the first and second positions (A and B), while C is the position of the model star, and *d* is the distance from the camera baseline

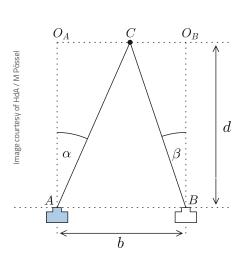


Figure 2: The model star, at position C, photographed from two different camera positions, A and B, separated by a shift of distance b

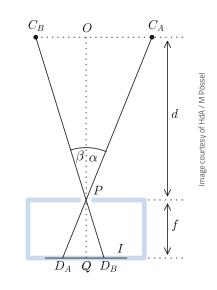


Figure 3: Simplified model of the parallax setup

to the star – that is, the distance we are trying to calculate.

The steps for calculating the distance d are set out below.

1. If we a draw a line that is parallel to the baseline and at the same distance *d* as the star, the camera's line of sight from position A will intersect the new line at OA, and from position B at OB. The angles between the camera's lines of sight and the direction to the star at camera positions A and B are  $\alpha$  and  $\beta$ , respectively.

Unlike theodolites, cameras do not allow us to measure angles directly. We thus need to relate the location of the images of the star on the camera's image detector screen to the angle of the light rays from the star when the camera is in different positions.

- 2. To do this, we need to think of the situation in a slightly simplified and fictionalised way. First, we treat the lens in the camera as a pinhole as shown in figure 3, where P is the position of the lens. So a light ray from the star travels in a straight line through the camera lens and hits the photographic detector on the imaging screen at a distance f (the focal length of the lens) behind the front of the camera.
- 3. Starting with figure 2, we then think about the situation from the point of view of the camera as it is moved from A to B – as if we were an observer sitting on the camera throughout. We can achieve this by, in effect, shifting the position of the camera position A (and the line AC) to the right by the distance *b* that the camera was moved, so that the two camera positions now coincide. The viewpoint of the camera

is shown in figure 3. The star's apparent location will be at location  $C_A$  when the camera is at the first position (A), and its image will be located at  $D_A$  on the detector screen. Similarly, after moving the camera to B, the star's apparent

location will be at  $C_B$  and its image at  $D_B$ . (Here, the line segment OQ represents the distance between the camera's image plane and the parallel plane that contains the star.) The length  $C_B C_A$  is the distance *b* in figure 2, while the angles  $\alpha$  and  $\beta$ remain the same.

4. Looking at the geometry, we can see some similar triangles. Using these triangles yields a formula linking the distance *d* to the other known lengths *b* and *f*, allowing us to calculate its value. You can find out how to derive this formula on the *Science in School* website<sup>w1.</sup>

The formula is:

$$d = \frac{p_{\rm L} \, \mathbf{x} \, d_{\rm L} \, \mathbf{x} \, b}{L \, x \, p}$$

where:

d = distance to star

- *L* = actual length of the calibration object
- b = actual distance the camera was moved (which corresponds to the distance from  $C_{A}$  to  $C_{R}$ )
- *d*<sub>L</sub> = actual distance of the calibration object from the camera baseline (along line OQ)
- p = distance as the number of pixels between the star images (at  $D_A$  and  $D_B$ )
- $p_{\rm L}$  = length as the number of pixels of the image of the calibration object
- To use this formula, you first need to use an image processing programme to find *p*, the number of pixels (on the horizontal axis) that separate the positions of the star's image between the two photos when you view them on screen. You can also use the programme to find *p*<sub>L</sub> the length of the calibration object as the number of pixels on screen.

When you have worked out a value for *d*, you have successfully used parallax measurement to determine the distance to the star.

Now use the tape measure to find the distance *d* directly, and compare this to the value calculated from the parallax measurement. How accurate was the calculated measurement?

You can repeat this activity with the 'star' placed at different distances, to find out whether the accuracy of parallax measurements changes with distance (see section below, 'What accuracy can we expect?').

# Parallax photography with a reference point

For even more astronomical realism, we can adapt the parallax photography method to use a reference object outside the classroom, which should be considerably further away than the 'star'. With this procedure, instead of relying on the camera pointing in the same direction after having been moved from A to B, we choose a distant reference object that is visible in each of the two images. We then measure the star image's pixel distance from the reference object in each image. This alternative approach, which we describe here, should yield more accurate results.

### Procedure

- For the reference object, find a small feature of the most distant object visible in both images – this must be much more distant than the model star. In our case, we chose a reference feature on one of the observatory domes of the Max Planck Institute for Astronomy as a marker, which was located about 80 m from our camera.
- 2. Draw a vertical line through the reference feature in each image. This is the reference line. We can

Image courtesy of HdA / M Pössel

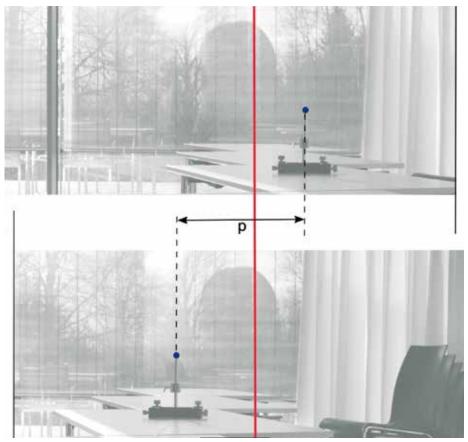


Figure 4. Two sample images from the camera activity, showing a horizontal pixel shift p. In the images, the reference object (a feature on the dome in the background) lies on the red reference line.

now use the reference line to find the pixel shifts between the two images, as shown in figure 4.

- 3. To work out *p*, the on-screen distance in pixels, you first need to find the model star's horizontal pixel distance from the reference line in both images separately. Then simply add these (corrected) horizontal pixel values to each other to find *p*. For example, –24 px would be 24 pixels to the left of the reference mark, while +36 px is 36 pixels to the right, giving a distance *p* of 60 pixels.
- From this point onwards, the calculations are the same as in the earlier method (see the section above, 'Calculating the star distance').

# What accuracy can we expect?

So, how accurate are the results obtained using this improved method? Our data suggest that they can be remarkably accurate (compared with directly measured distances), as shown in figure 5. The largest relative error amounts to just 3.2%.

Note that, at larger distances, there is an increase in the relative error as well as the actual error. This is because the geometry changes: the distance to the model star becomes larger compared with the distance of the reference object, so the error introduced by the parallax of the reference object becomes ever greater.

With the simple angle-measuring method described in the previous article (Pössel, 2017), the accuracy of distance measurements was significantly lower – generally within about 10%, as shown in figure 6. So the method described in the current article provides a significant improvement in accuracy from the previous method, where the dominant sources of error are the angular measurements.

### Reference

Pössel M (2017) Parallax: reaching the stars with geometry. *Science in School* **39**: 40-44. www. scienceinschool.org/2017/issue39/parallax

#### Web reference

w1 An algebraic derivation of the formula for calculating the star distance using similar triangles can be downloaded from the *Science in School* website. See: www. scienceinschool.org/2017/issue40/parallax

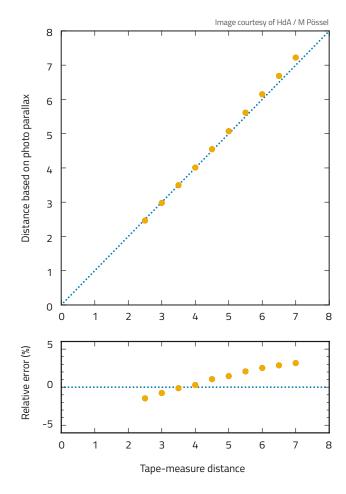


Figure 5: Top: distances to the model star measured by the parallax method plotted against tape-measure distances

Bottom: relative errors of distances measured using the reference point parallax photograph method, compared to the tape-measure distances

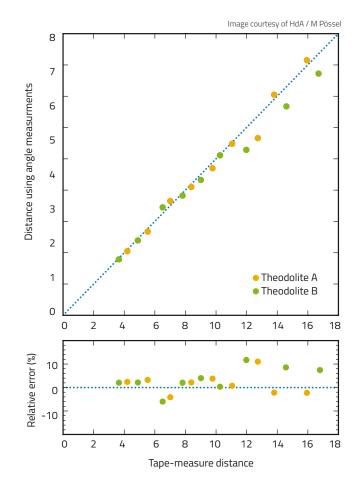


Figure 6: Top: parallax distances measured using theodolites plotted against tape-measure distances. (For perfect accuracy, all data points would lie on the dotted line.)

Bottom: relative errors of distances measured using the theodolites, compared to the tape-measure distances

#### Resources

For information on how to carry out real

astronomical parallax measurements with small instruments, see:

Cenadelli D et al. (2016) Geometry can take you to the Moon. *Science in School* **35**: 41-46. www.scienceinschool.org/2016/issue35/ parallax

Cenadelli D et al. (2009) An international parallax campaign to measure distance to the Moon and Mars. European Journal of Physics 30: 35-46. doi: 10.1088/0143-0807/30/1/004

Hirshfeld AW (2013) Parallax: The Race to Measure the Cosmos. Mineola, NY, USA: Dover Publications. ISBN: 9780486490939

Variations of these experiments have been in use in astronomy laboratory courses for a long time. For example:

De Jong ML (1972) A stellar parallax exercise for the introductory astronomy course. American Journal of Physics 40(5): 762-763. doi: 10.1119/1.1986635

Deutschman WA (1977) Parallax without pain. American Journal of Physics 45(5): 490. doi: 10.1119/1.11009

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